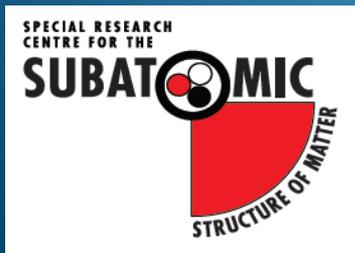


The new method to extract the spectra of irreducible representations of lattice

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Collaborate: Derek B. Leinweber, Ross D. Young, and James M. Zanotti

The University of Adelaide
CSSM



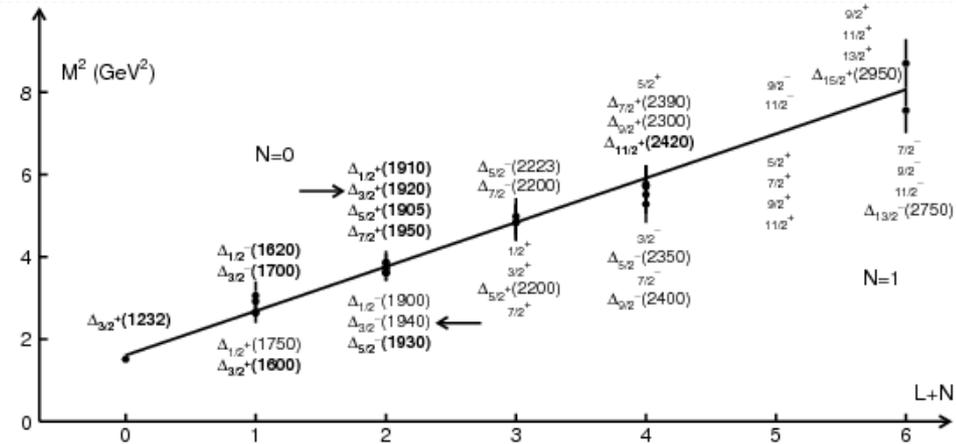
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Outline

- Motivation
- New method
- Pion-Pion with $I=2$
- Summary and Outlook

Motivation : How important of High partial wave state

- Regge Trajectory



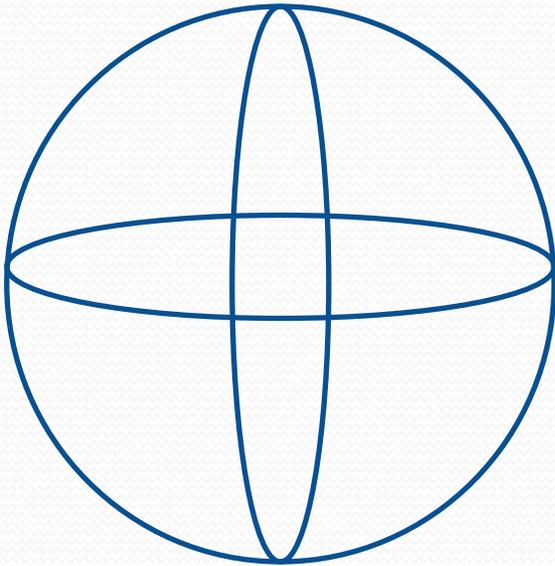
- High momentum cross section

$$\sigma \sim p^{2l+1}$$

- Nucleon-Nuclei scattering

P wave phase shifts are the key of “ A_y -puzzle” in nucleon-deuteron scattering.

Motivation : How to get High partial wave state in the finite volume ??

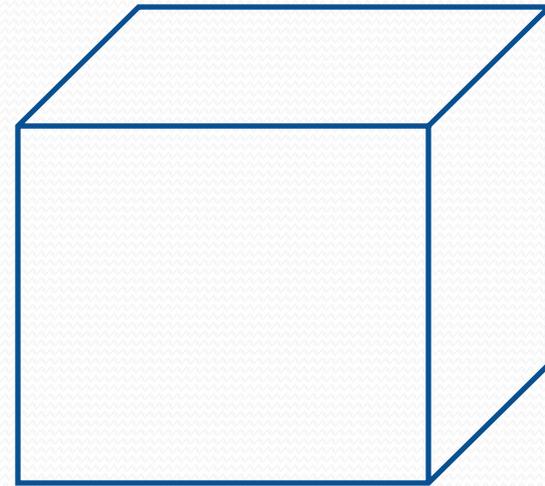


Symmetry

$SO(3)$

$L^P = 0^+, 1^-, 2^+, 3^-,$

.....



O_h

$A_1^\pm, A_2^\pm, E^\pm, T_1^\pm, T_2^\pm$

Motivation : Infinite \leftrightarrow Finite

SO(3)	O_h
0 ⁺	A ₁ ⁺
1 ⁻	T ₁ ⁻
2 ⁺	E ⁺ ⊕ T ₂ ⁺
3 ⁻	A ₂ ⁻ ⊕ T ₁ ⁻ ⊕ T ₂ ⁻
4 ⁺	A ₁ ⁺ ⊕ E ⁺ ⊕ T ₁ ⁺ ⊕ T ₂ ⁺
5 ⁻	E ⁻ ⊕ 2T ₁ ⁻ ⊕ T ₂ ⁻
6 ⁺	A ₁ ⁺ ⊕ A ₂ ⁺ ⊕ E ⁺ ⊕ T ₁ ⁺ ⊕ 2T ₂ ⁺
7 ⁻	A ₂ ⁻ ⊕ E ⁻ ⊕ 2T ₁ ⁻ ⊕ 2T ₂ ⁻
8 ⁺	A ₁ ⁺ ⊕ 2E ⁺ ⊕ 2T ₁ ⁺ ⊕ 2T ₂ ⁺
9 ⁻	A ₁ ⁻ ⊕ A ₂ ⁻ ⊕ E ⁻ ⊕ 3T ₁ ⁻ ⊕ 2T ₂ ⁻

O_h	SO(3)
A ₁ ⁺	0 ⁺ , 4 ⁺ , 8 ⁺ ,
A ₂ ⁺	6 ⁺ ,
E ⁺	2 ⁺ , 4 ⁺ , 6 ⁺ , 8 ⁺ ,
T ₁ ⁺	4 ⁺ , 6 ⁺ , 8 ⁺ ,
T ₂ ⁺	2 ⁺ , 4 ⁺ , 6 ⁺ , 8 ⁺ ,
A ₁ ⁻	9 ⁻ ,
A ₂ ⁻	3 ⁻ , 7 ⁻ , 9 ⁻ ,
E ⁻	5 ⁻ , 7 ⁻ , 9 ⁻ ,
T ₁ ⁻	1 ⁻ , 3 ⁻ , 5 ⁻ , 7 ⁻ , 9 ⁻ ,
T ₂ ⁻	3 ⁻ , 5 ⁻ , 7 ⁻ , 9 ⁻ ,

Motivation : Infinite \leftrightarrow Finite

SO(3)	O _h
0 ⁺	A ₁ ⁺
1 ⁻	T ₁ ⁻
2 ⁺	E ⁺ ⊕ T ₂ ⁺
3 ⁻	A ₂ ⁻ ⊕ T ₁ ⁻ ⊕ T ₂ ⁻
4 ⁺	A ₁ ⁺ ⊕ E ⁺ ⊕ T ₁ ⁺ ⊕ T ₂ ⁺
5 ⁻	E ⁻ ⊕ 2T ₁ ⁻ ⊕ T ₂ ⁻
6 ⁺	A ₁ ⁺ ⊕ A ₂ ⁺ ⊕ E ⁺ ⊕ T ₁ ⁺ ⊕ 2T ₂ ⁺
7 ⁻	A ₂ ⁻ ⊕ E ⁻ ⊕ 2T ₁ ⁻ ⊕ 2T ₂ ⁻
8 ⁺	A ₁ ⁺ ⊕ 2E ⁺ ⊕ 2T ₁ ⁺ ⊕ 2T ₂ ⁺
9 ⁻	A ₁ ⁻ ⊕ A ₂ ⁻ ⊕ E ⁻ ⊕ 3T ₁ ⁻ ⊕ 2T ₂ ⁻

O _h	SO(3)
A ₁ ⁺	0 ⁺ , 4 ⁺ , 8 ⁺ , ...
A ₂ ⁺	6 ⁺ , ...
E ⁺	2 ⁺ , 4 ⁺ , 6 ⁺ , 8 ⁺ , ...
T ₁ ⁺	4 ⁺ , 6 ⁺ , 8 ⁺ , ...
T ₂ ⁺	2 ⁺ , 4 ⁺ , 6 ⁺ , 8 ⁺ , ...
A ₁ ⁻	9 ⁻ , ...
A ₂ ⁻	3 ⁻ , 7 ⁻ , 9 ⁻ , ...
E ⁻	5 ⁻ , 7 ⁻ , 9 ⁻ , ...
T ₁ ⁻	1 ⁻ , 3 ⁻ , 5 ⁻ , 7 ⁻ , 9 ⁻ , ...
T ₂ ⁻	3 ⁻ , 5 ⁻ , 7 ⁻ , 9 ⁻ , ...

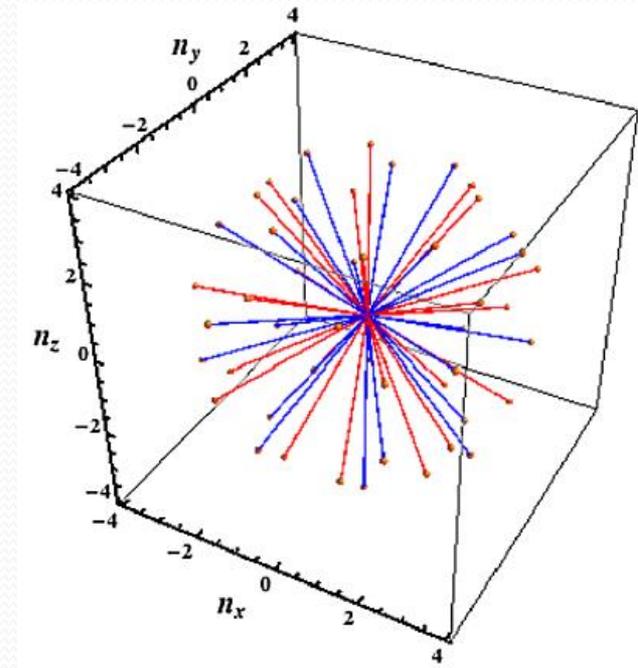
For the High Partial Wave scattering amplitudes, we need the spectra of various irreducible representations.

New Method: Rotation of O_h

Question: How to express the rotation elements of O_h group ?

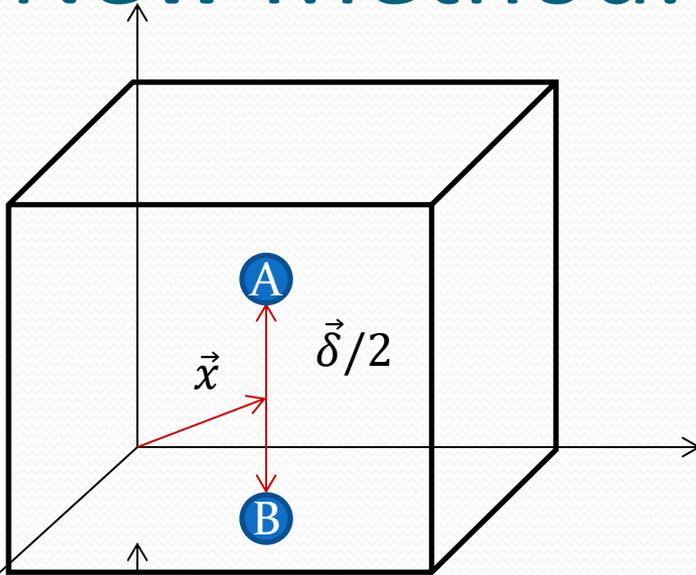
There are 48 rotation elements which can connect 48 vectors in the coordinate space.

\hat{R}	Rotation Axis	Rotation Angle	(x_1, x_2, x_3)
\hat{R}_1	Any	0°	(x_1, x_2, x_3)
\hat{R}_2	$(1, 1, 1)$	-120°	(x_2, x_3, x_1)
...
\hat{R}_{24}	$(0, 0, 1)$	-180°	$(-x_1, -x_2, x_3)$
$\hat{R}_{25} = \hat{\pi} \hat{R}_1$	-	-	$(-x_1, -x_2, -x_3)$
$\hat{R}_{26} = \hat{\pi} \hat{R}_2$	-	-	$(-x_2, -x_3, -x_1)$
...
$\hat{R}_{48} = \hat{\pi} \hat{R}_{24}$	-	-	$(x_1, x_2, -x_3)$



T. Luu and M. J. Savage,
PRD 83 114508(2011)

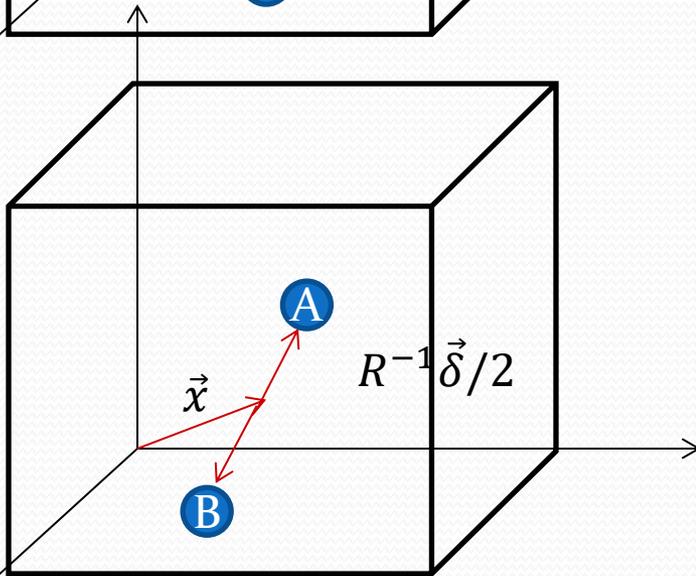
New Method: Two body Operator



$$\phi(\vec{x}, \vec{\delta}, t) = \chi_A(\vec{x} + \vec{\delta}/2, t) \chi_B(\vec{x} - \vec{\delta}/2, t)$$



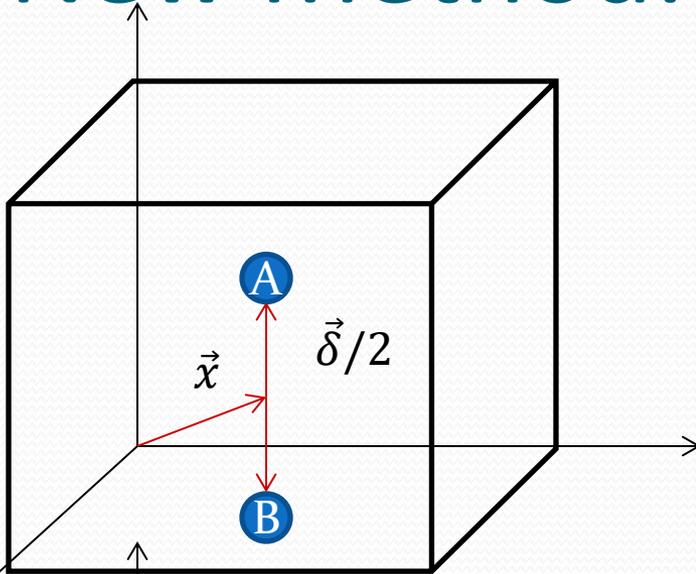
Rotation Elements: $\hat{R} = \{\hat{R}_1, \hat{R}_2, \dots, \hat{R}_{48}\}$



$$\phi_R(\vec{x}, \vec{\delta}, t) = \chi_A(\vec{x} + R^{-1} \vec{\delta}/2, t) \chi_B(\vec{x} - R^{-1} \vec{\delta}/2, t)$$

There are 48 different two particles operator, ϕ_R .

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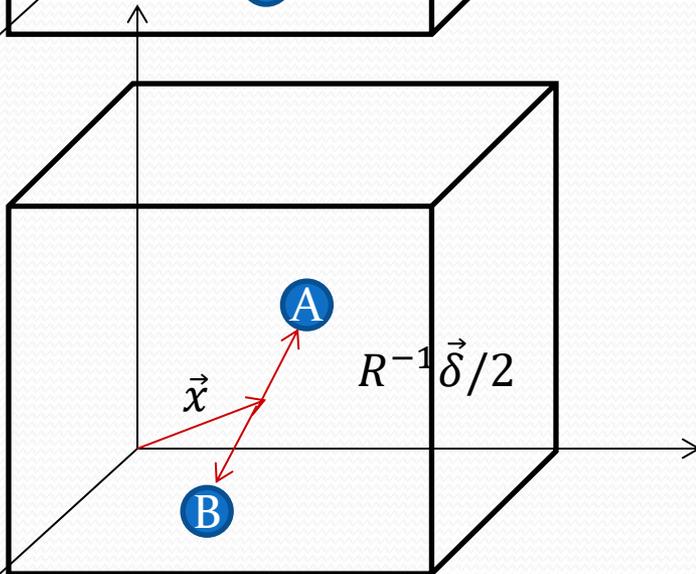


Rotation Elements: $\hat{R} = \{\hat{R}_1, \hat{R}_2, \dots, \hat{R}_{48}\}$

$$\vec{\delta} = (\delta_x, \delta_y, \delta_z)$$

$$\delta_x \neq \delta_y \neq \delta_z$$

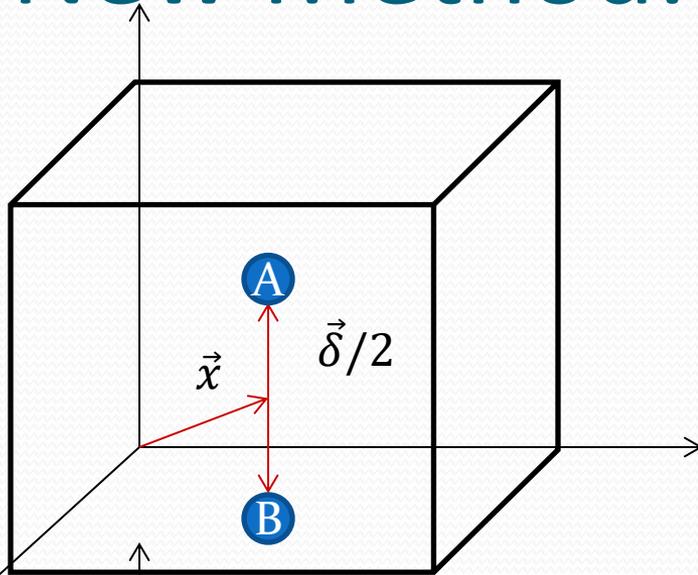
$$\vec{x} \pm \vec{\delta}/2 = \vec{n} \in \mathbb{Z}^3$$



$$\phi_R(\vec{x}, \vec{\delta}, t) = \chi_A(\vec{x} + R^{-1}\vec{\delta}/2, t) \chi_B(\vec{x} - R^{-1}\vec{\delta}/2, t)$$

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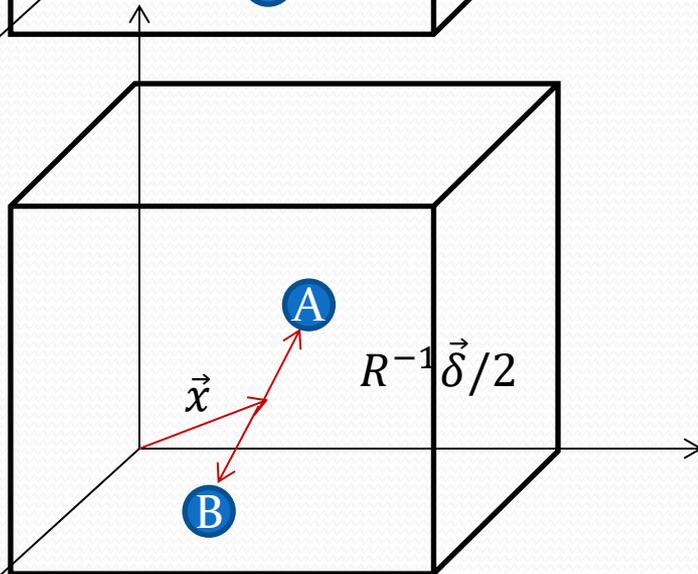
$$\vec{\delta} = (\delta_x, \delta_y, \delta_z)$$

$$\delta_x \neq \delta_y \neq \delta_z$$

$$\vec{x} \pm \vec{\delta}/2 = \vec{n} \in \mathbb{Z}^3$$

$$\vec{x} = \left(\frac{1}{2}, \frac{1}{2}, \frac{1}{2}\right) \text{ and } \vec{\delta} = (1, 3, 5)$$

Simplifies continuum rotation symmetry



$$\phi_R(\vec{x}, \vec{\delta}, t) = \chi_A(\vec{x} + R^{-1}\vec{\delta}/2, t) \chi_B(\vec{x} - R^{-1}\vec{\delta}/2, t)$$

There are 48 different two particles operator, ϕ_R .

New Method: Basis State (1)

$$\phi_R^+(\vec{x}, \vec{\delta}, t)|\Omega\rangle = |\phi_R^+(\vec{x}, \vec{\delta}, t)\rangle \sim |\phi_R^+(\vec{\delta})\rangle$$

$$\hat{R}_X |\phi_R^+(\vec{\delta})\rangle = |\phi_{R_X R}^+(\vec{\delta})\rangle = \sum_{R'} |\phi_{R'}^+(\vec{\delta})\rangle [\bar{\Gamma}_{reg}(R_X)]_{R'R}$$

Matrix $\bar{\Gamma}_{reg}(R_X)$ is one of the matrices of representation of O_h group, and it is 48×48 matrix. Obviously, there are 48 matrices of $\bar{\Gamma}_{reg}$ corresponding to 48 rotation elements of O_h group. The representation matrices $\bar{\Gamma}_{reg}$ use **all the elements** of the group as multipliers, and the dimension of it equal to the order of the group. This representation is called “**regular representation**”.

Regular representation $\bar{\Gamma}_{reg}$ is a reducible representation, it can be reduced to several **irreducible representations** through similarity transformation:

$$S^{-1} \bar{\Gamma}_{reg}(R_X) S = A_1^+ \oplus A_2^+ \oplus 2E^+ \oplus 3T_1^+ \oplus 3T_2^+ \\ \oplus A_1^- \oplus A_2^- \oplus 2E^- \oplus 3T_1^- \oplus 3T_2^-$$

New Method: Basis State (2)

$$\hat{R}_X |\phi_R^+(\vec{\delta})\rangle = |\phi_{R_X R}^+(\vec{\delta})\rangle = \sum_{R'} |\phi_{R'}^+(\vec{\delta})\rangle [\bar{\Gamma}_{reg}(R_X)]_{R'R}$$

$$S^{-1} \bar{\Gamma}_{reg} S = A_1^+ \oplus A_2^+ \oplus 2E^+ \oplus 3T_1^+ \oplus 3T_2^+ \\ \oplus A_1^- \oplus A_2^- \oplus 2E^- \oplus 3T_1^- \oplus 3T_2^-$$

$$48 = 1 + 1 + 2 \times 2 + 3 \times 3 + 3 \times 3 \\ + 1 + 1 + 2 \times 2 + 3 \times 3 + 3 \times 3$$

e.g.

i: 1, 2 i: 1, 2, 3

Γ : E Γ : T_2

n: 1, 2 n: 1, 2, 3

This block-diagonal matrices will lead to a new set of basis states:

$$|\Phi_{i,\Gamma,n}^+(\vec{\delta})\rangle$$

New Method: Basis State (3)

$$\hat{R}_X |\phi_R^+(\vec{\delta})\rangle = |\phi_{R_X R}^+(\vec{\delta})\rangle = \sum_{R'} |\phi_{R'}^+(\vec{\delta})\rangle [\bar{\Gamma}_{reg}(R_X)]_{R'R}$$

$$S^{-1} \bar{\Gamma}_{reg} S = A_1^+ \oplus A_2^+ \oplus 2E^+ \oplus 3T_1^+ \oplus 3T_2^+ \\ \oplus A_1^- \oplus A_2^- \oplus 2E^- \oplus 3T_1^- \oplus 3T_2^-$$

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n: 1, 2 n: 1, 2, 3

This block-diagonal matrices will lead to a new set of basis states: $|\Phi_{i,\Gamma,n}^+(\vec{\delta})\rangle$

$$\hat{R}_X |\Phi_{i,\Gamma,n}^+(\vec{\delta})\rangle = \sum_{i',\Gamma',n'} |\Phi_{i',\Gamma',n'}^+(\vec{\delta})\rangle [S^{-1} \bar{\Gamma}_{reg}(R_X) S]_{i'\Gamma'n', i\Gamma n}$$

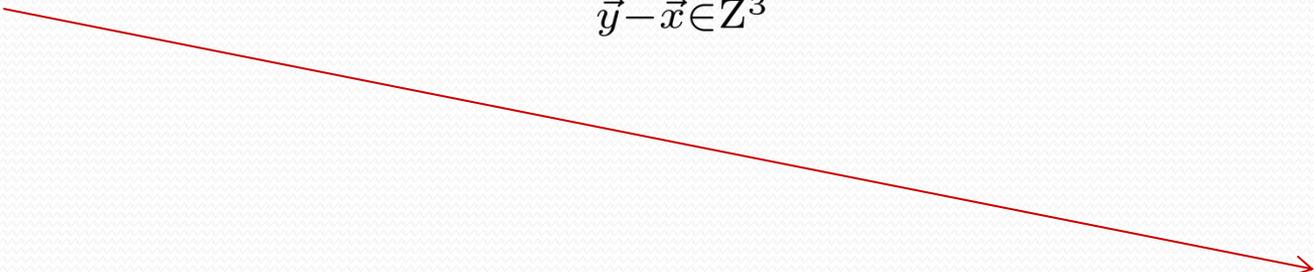
$$|\phi_R^+(\vec{\delta})\rangle \longrightarrow |\Phi_{i,\Gamma,n}^+(\vec{\delta})\rangle$$

$$|\Phi_{i,\Gamma,n}^+(\vec{\delta})\rangle = \sum_R |\phi_R^+(\vec{\delta})\rangle [S]_{R, i\Gamma n}$$

New Method: Correlation Function(1)

The correlation function is:

$$G_{R,R'}(\vec{p} = 0, \vec{y}, \vec{x}, \vec{\delta}, t) = \sum_{\vec{y}-\vec{x} \in \mathbb{Z}^3} e^{\vec{p} \cdot (\vec{y}-\vec{x})} \langle \Omega | \phi_R(\vec{y}, \vec{\delta}, t) \phi_{R'}^\dagger(\vec{x}, \vec{\delta}, 0) | \Omega \rangle$$



48×48

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$$\sim \sum_{\vec{y}-\vec{x} \in \mathbb{Z}^3} \langle \phi_R^\dagger(\vec{y}, \vec{\delta}, 0) | e^{-\hat{H}t} | \phi_{R'}^\dagger(\vec{x}, \vec{\delta}, 0) \rangle \sim \sum \langle \phi^\dagger(R^{-1}\vec{\delta}) | e^{-\hat{H}t} | \phi^\dagger(R'^{-1}\vec{\delta}) \rangle$$

$$[\hat{R}_x, \hat{H}] = 0$$

48×48

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48×48

$$\begin{aligned} & \sum \langle \phi^\dagger(R\vec{\delta}) | e^{-\hat{H}t} | \phi^\dagger(\vec{\delta}) \rangle \\ &= \sum \langle \phi^\dagger(RR'\vec{\delta}) | e^{-\hat{H}t} | \phi^\dagger(R'\vec{\delta}) \rangle \\ &= \sum \langle \phi^\dagger(R'R\vec{\delta}) | e^{-\hat{H}t} | \phi^\dagger(R'\vec{\delta}) \rangle \\ &= \sum \langle \phi^\dagger(R'RR'^{-1}\vec{\delta}) | e^{-\hat{H}t} | \phi^\dagger(\vec{\delta}) \rangle \end{aligned}$$

E, π
8C ₃ , 8C ₃ π
3C ₂ , 3C ₂ π
6C ₄ , 6C ₄ π
6C' ₂ , 6C' ₂ π

The operators in the same class has the same value of correlation function

New Method: Correlation Function(1)

The correlation function is:

$$G_{R,R'}(\vec{p} = 0, \vec{y}, \vec{x}, \vec{\delta}, t) = \sum_{\vec{y}-\vec{x} \in \mathbb{Z}^3} e^{\vec{p} \cdot (\vec{y}-\vec{x})} \langle \Omega | \phi_R(\vec{y}, \vec{\delta}, t) \phi_{R'}^\dagger(\vec{x}, \vec{\delta}, 0) | \Omega \rangle$$

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E, π
$8C_3, 8C_3\pi$
$3C_2, 3C_2\pi$
$6C_4, 6C_4\pi$
$6C'_2, 6C'_2\pi$

48×48



10

The operators in the same class has the same value of correlation function

New Method: Correlation Function(2)

The correlation function is:

$$\sum_{\vec{y}-\vec{z}\in\mathbb{Z}^3} e^{\vec{p}\cdot(\vec{y}-\vec{x})} \langle \Omega | \Phi_{i,\Gamma,n}(\vec{y}, \vec{\delta}, t) \Phi_{i',\Gamma',n'}^\dagger(\vec{x}, \vec{\delta}, 0) | \Omega \rangle$$

$$|\Phi_{i,\Gamma,n}^+(\vec{\delta})\rangle = \sum_R |\phi_R^+(\vec{\delta})\rangle [S]_{R, i\Gamma n}$$

$$\sum \langle \phi^\dagger(R\vec{\delta}) | e^{-\hat{H}t} | \phi^\dagger(\vec{\delta}) \rangle = \sum \langle \phi^\dagger(R'RR'^{-1}\vec{\delta}) | e^{-\hat{H}t} | \phi^\dagger(\vec{\delta}) \rangle$$

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$$= \delta_{i,i'} \delta_{\Gamma,\Gamma'} \delta_{n,n'} \sum_{\vec{y}-\vec{x} \in \mathbb{Z}^3} e^{\vec{p} \cdot (\vec{y}-\vec{x})} \frac{h}{l_\Gamma} \sum_R \chi_\Gamma(R) \langle \Omega | \phi_R(\vec{y}, \vec{\delta}, t) \phi^\dagger(\vec{x}, \vec{\delta}, 0) | \Omega \rangle$$

$$|\Phi_{i,\Gamma,n}^+(\vec{\delta})\rangle = \sum_R |\phi_R^+(\vec{\delta})\rangle [S]_{R, i\Gamma n}$$

$$\sum \langle \phi^\dagger(R\vec{\delta}) | e^{-\hat{H}t} | \phi^\dagger(\vec{\delta}) \rangle = \sum \langle \phi^\dagger(R'RR'^{-1}\vec{\delta}) | e^{-\hat{H}t} | \phi^\dagger(\vec{\delta}) \rangle$$

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Diagonal and
Just rely on Γ

Character
Number of Γ

h and l_Γ are the orders of Oh
group and irreducible
representation Γ .

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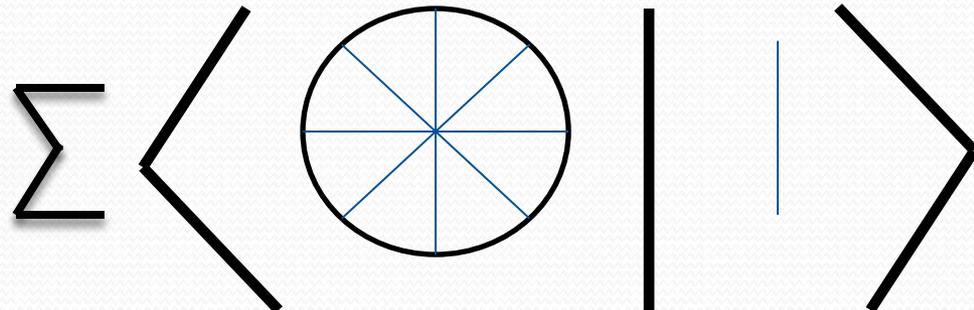
Diagonal and
Just rely on Γ

Character
Number of Γ

“Shell” Sink

Two source
locations as
 $\vec{x} + \frac{\vec{\delta}}{2}$ and $\vec{x} - \frac{\vec{\delta}}{2}$

h and l_Γ are the orders of Oh
group and irreducible
representation Γ .



Pion-Pion with $I=2$: Correlation function



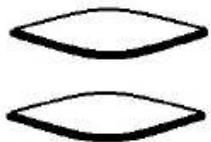
$$\chi_{\pi^-}(\vec{x}, t) = u(\vec{x}, t)\gamma_5\bar{d}(\vec{x}, t)$$

$$\phi_R(\vec{x}, \vec{\delta}, t) = \chi_{\pi^-}(\vec{x} + R^{-1}\vec{\delta}/2, t)\chi_{\pi^-}(\vec{x} - R^{-1}\vec{\delta}/2, t)$$

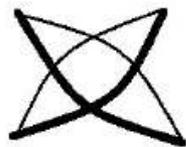
$L = 0^+, 2^+, 4^+, \dots$, and here we neglect $L > 4$

	E, π	$8C_3, 8C_3\pi$	$3C_2, 3C_2\pi$	$6C_4, 6C_4\pi$	$6C'_2, 6C'_2\pi$	L
A_1^+	1	1	1	1	1	$0^+, 4^+$
E^+	2	-1	2	0	0	$2^+, 4^+$
T_1^+	3	0	-1	-1	1	4^+
T_2^+	3	0	-1	1	-1	$2^+, 4^+$

$$G_\Gamma(\vec{y}, \vec{x}, \vec{\delta}, t) = \sum_{R \in O_h} \chi_\Gamma(R) \sum_{\vec{y} - \vec{x} \in \mathbb{Z}^3} \langle \Omega | \phi_R(\vec{y}, \vec{\delta}, t) \phi^\dagger(\vec{x}, \vec{\delta}, 0) | \Omega \rangle$$



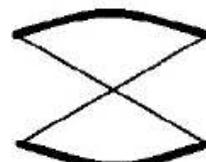
(a)



(b)



(c)

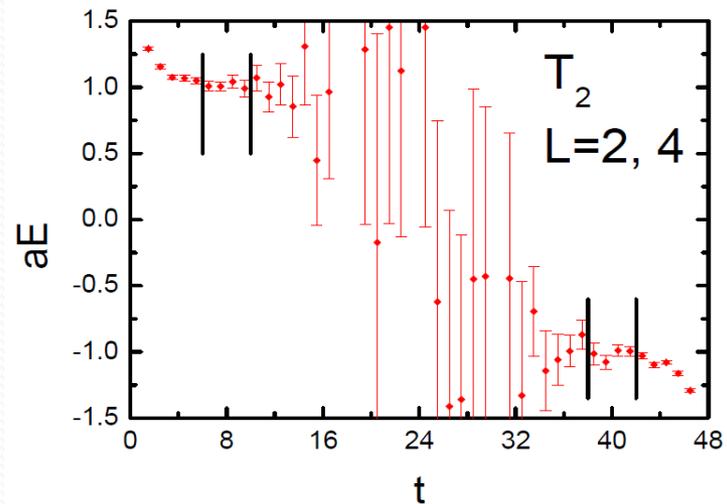
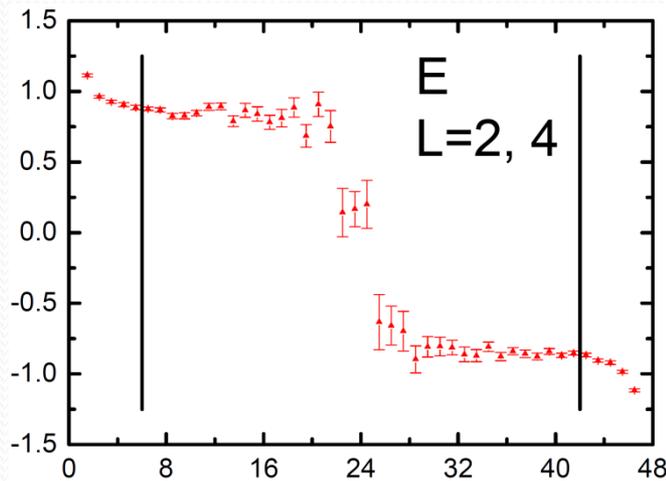
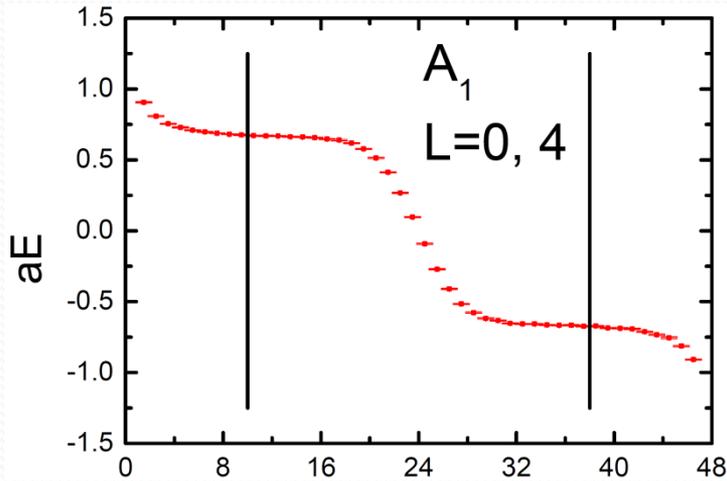


(d)

Thick lines: $\bar{u}u$
Thin lines: $\bar{d}d$

Pion-Pion with $l=2$: Spectra

The result of $L = 24^3 \times 48$ and $a = 0.07$ fm, $m_\pi = 900$ MeV



376 configurations and
16 source locations

$$p_\Gamma = \frac{1}{2} \sqrt{E_\Gamma^2 - 4m_\pi^2}$$

$$\frac{p_{A_1} L}{2\pi} = 0.2455(36) \\ \sim 0$$

$$\frac{p_E L}{2\pi} = 1.047(13) \\ \sim 1$$

$$\frac{p_{T_2} L}{2\pi} = 1.457(23) \\ \sim \sqrt{2}$$

Pion-Pion with I=2: Lüscher Equation

$$\det \begin{pmatrix} \text{ctg}\delta_0(p_{A_1}) + M_{11}^{A_1}(p_{A_1}) & M_{12}^{A_1}(p_{A_1}) \\ M_{12}^{A_1}(p_{A_1}) & \text{ctg}\delta_4(p_{A_1}) + M_{22}^{A_1}(p_{A_1}) \end{pmatrix} = 0$$

$$\det \begin{pmatrix} \text{ctg}\delta_2(p_E) + M_{11}^E(p_E) & M_{12}^E(p_E) \\ M_{12}^E(p_E) & \text{ctg}\delta_4(p_E) + M_{22}^E(p_E) \end{pmatrix} = 0$$

$$\det \begin{pmatrix} \text{ctg}\delta_2(p_{T_2}) + M_{11}^{T_2}(p_{T_2}) & M_{12}^{T_2}(p_{T_2}) \\ M_{12}^{T_2}(p_{T_2}) & \text{ctg}\delta_4(p_{T_2}) + M_{22}^{T_2}(p_{T_2}) \end{pmatrix} = 0$$

$$M_{ij}^\Gamma(p) = \sum_s C_{i,j,s}^\Gamma H_{s0}\left(\frac{pL}{2\pi}\right)$$

$$H_{s0}(q) = \frac{Z_{s0}(1; q)}{\sqrt{(2s+1)\pi^3} q^{s+1}}$$

But only **3** equations, but **6** different phase shifts,
 $\delta_0(p_{A_1}), \delta_4(p_{A_1}), \delta_2(p_E), \delta_4(p_E), \delta_2(p_{T_2}), \delta_4(p_{T_2})$.

Γ	(i,j)	(s, $C_{i,j,s}^\Gamma$)
A_1^+	(1,1)	(0,1)
	(1,2)	(4, $\frac{6\sqrt{21}}{7}$)
	(2,2)	(0,1), (4, $\frac{324}{143}$), (6, $\frac{80}{11}$), (8, $\frac{560}{143}$)
E^+	(1,1)	(0,1), (4, $\frac{18}{7}$)
	(1,2)	(4, $-\frac{120\sqrt{3}}{77}$), (6, $-\frac{30\sqrt{3}}{11}$)
	(2,2)	(4, $\frac{324}{1001}$), (6, $-\frac{64}{11}$), (8, $\frac{392}{143}$)
T_1^+	(1,1)	(0,1), (4, $-\frac{12}{7}$)
	(1,2)	(4, $-\frac{60\sqrt{3}}{77}$), (6, $\frac{40\sqrt{3}}{11}$)
	(2,2)	(0,1), (4, $-\frac{162}{77}$), (6, $\frac{20}{11}$)

Pion-Pion with I=2: Toy Model

By fitting experimental data up to $p = 600$ MeV, for $L=0, 2, 4$ partial wave, the phase shifts can be expressed as

$$p^{2L+1} \cot \delta_l(p) = \frac{1}{a_L} + \frac{1}{2} r_L p^2$$

$$a_0 = -0.8 \text{GeV}^{-1}, \quad r_0 = +2.5 \text{GeV}^{-1}$$

$$a_2 = -2.4 \text{GeV}^{-5}, \quad r_2 \equiv 0$$

$$a_4 = -5.0 \text{GeV}^{-9}, \quad r_4 \equiv 0$$

W. Hoogland, *ect NPB* 126 106 (1977)

D. H. Cohen, *ect PRD* 7 661 (1973)

A. Zieminski, *ect NPB* 69 502 (1974)

N. Durusa, *ect PLB* 45 517 (1973)

J. J. Dudek, *ect PRD* 86 034031(2012)

$$\det \begin{pmatrix} \cot \delta_0(p_{A_1}) + M_{11}^{A_1}(p_{A_1}) & M_{12}^{A_1}(p_{A_1}) \\ M_{12}^{A_1}(p_{A_1}) & \cot \delta_4(p_{A_1}) + M_{22}^{A_1}(p_{A_1}) \end{pmatrix} = 0$$

$$\det \begin{pmatrix} \cot \delta_2(p_E) + M_{11}^E(p_E) & M_{12}^E(p_E) \\ M_{12}^E(p_E) & \cot \delta_4(p_E) + M_{22}^E(p_E) \end{pmatrix} = 0$$

$$\det \begin{pmatrix} \cot \delta_2(p_{T_2}) + M_{11}^{T_2}(p_{T_2}) & M_{12}^{T_2}(p_{T_2}) \\ M_{12}^{T_2}(p_{T_2}) & \cot \delta_4(p_{T_2}) + M_{22}^{T_2}(p_{T_2}) \end{pmatrix} = 0$$

Pion-Pion with I=2: Toy Model

By fitting experimental data up to $p = 600$ MeV, for $L=0, 2, 4$ partial wave, the phase shifts can be expressed as

$$p^{2L+1} \text{Cot} \delta_l(p) = \frac{1}{a_L} + \frac{1}{2} r_L p^2$$

$$a_0 = -0.8 \text{GeV}^{-1}, \quad r_0 = +2.5 \text{GeV}^{-1}$$

$$a_2 = -2.4 \text{GeV}^{-5}, \quad r_2 \equiv 0$$

$$a_4 = -5.0 \text{GeV}^{-9}, \quad r_4 \equiv 0$$

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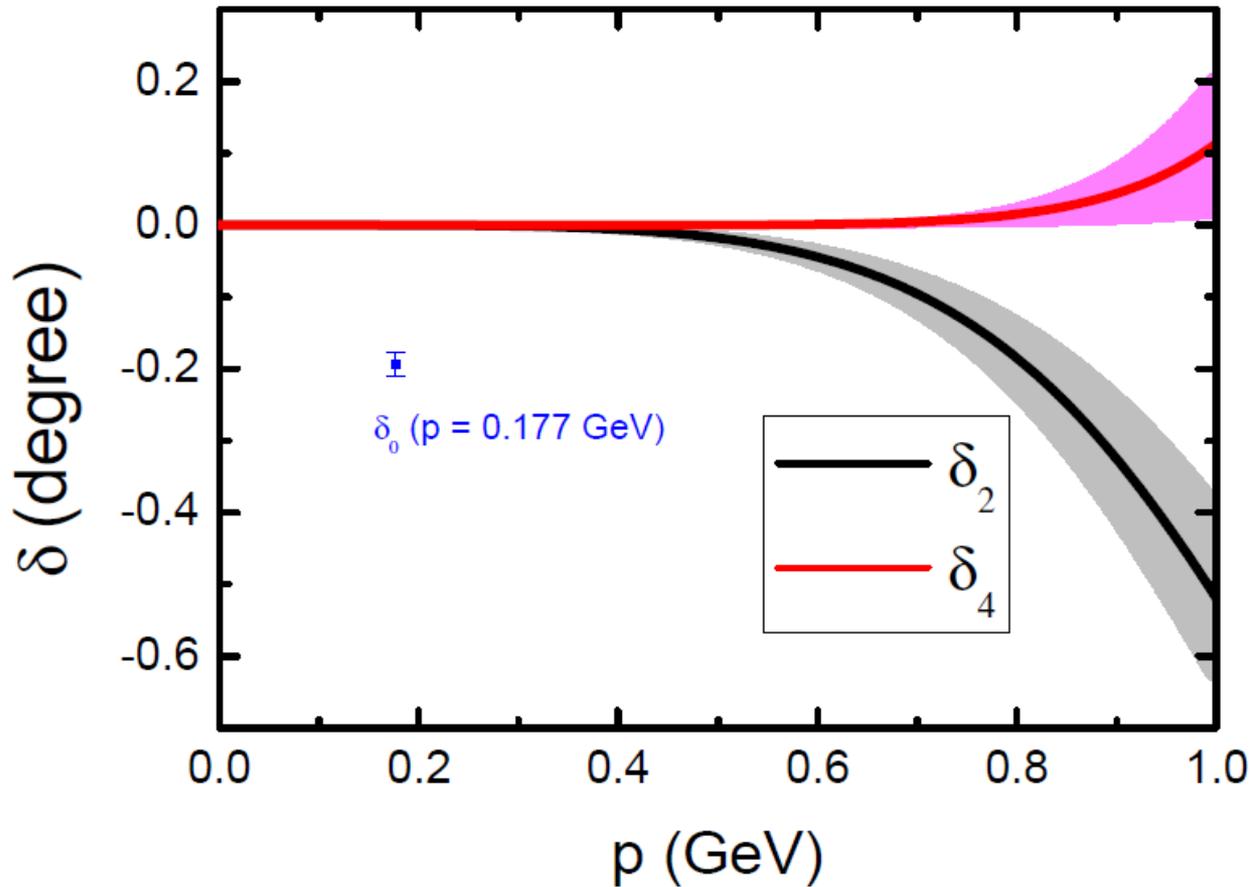
$$\det \begin{pmatrix} \cot \delta_0(p_{A_1}) + M_{11}^{A_1}(p_{A_1}) & M_{12}^{A_1}(p_{A_1}) \\ M_{12}^{A_1}(p_{A_1}) & \frac{1}{a_4 p_{A_1}^9} + M_{22}^{A_1}(p_{A_1}) \end{pmatrix} = 0$$

$$\det \begin{pmatrix} \frac{1}{a_2 p_E^5} + M_{11}^E(p_E) & M_{12}^E(p_E) \\ M_{12}^E(p_E) & \frac{1}{a_4 p_E^9} + M_{22}^E(p_E) \end{pmatrix} = 0$$

$$\det \begin{pmatrix} \frac{1}{a_2 p_{T_2}^5} + M_{11}^{T_2}(p_{T_2}) & M_{12}^{T_2}(p_{T_2}) \\ M_{12}^{T_2}(p_{T_2}) & \frac{1}{a_4 p_{T_2}^9} + M_{22}^{T_2}(p_{T_2}) \end{pmatrix} = 0$$

$$\delta_0(p_{A_1}), \quad a_2, \quad a_4$$

Pion-Pion with $l=2$: Phase Shift



$$p^{2L+1} \text{Cot} \delta_l(p) = \frac{1}{a_L}$$

$$a_2 = -0.571 \pm 0.155 \text{ GeV}^{-5}$$

$$a_4 = 0.114 \pm 0.100 \text{ GeV}^{-9}$$

$$\delta(p_{A_1} = 0.177 \text{ GeV})$$

$$= -0.190 \pm 0.017$$

Summary

- In the coordinate space, we develop a new method to extract spectra of irreducible representation in the finite volume. It just cost two source inversions per measurement.
- We apply this method for $\pi\pi$ system with $I=2$ in the rest frame. It successfully generates signals of ground state of A1, E, and T2 representation. Then we can get phase shifts through Lüscher equation and toy model.

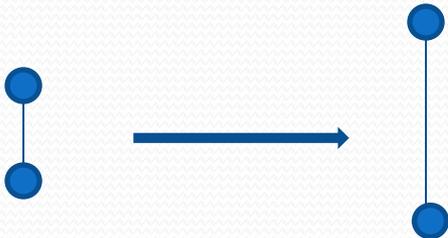
Outlook

- This method is also useful for boost frame. It just replace little group for boost frame instead of O_h group.



- For the excited states in the each irreducible representation, we need to develop more two particle operators and use variational method.

Operators basis distinguished by different $\vec{\delta}$.





Thanks for attention

New Method: Basis State (2)

$$\phi_R^+(\vec{x}, \vec{\delta}, t)|\Omega\rangle = |\phi_R^+(\vec{x}, \vec{\delta}, t)\rangle \sim |\phi_R^+(\vec{\delta})\rangle$$

$$\hat{R}_X |\phi_R^+(\vec{\delta})\rangle = |\phi_{R_X R}^+(\vec{\delta})\rangle = \sum_{R'} |\phi_{R'}^+(\vec{\delta})\rangle [\bar{\Gamma}_{reg}(R_X)]_{R'R}$$

$\bar{\Gamma}_{reg}$ is “**regular representation**”.

It can be reduced to several **irreducible representations** :

$$S^{-1} \bar{\Gamma}_{reg} S = A_1^+ \oplus A_2^+ \oplus 2E^+ \oplus 3T_1^+ \oplus 3T_2^+ \\ \oplus A_1^- \oplus A_2^- \oplus 2E^- \oplus 3T_1^- \oplus 3T_2^-$$

$$|\Phi_{i,\Gamma,n}^+(\vec{\delta})\rangle$$

i: 1, 2

Γ : E

n: 1, 2

i: 1, 2, 3

Γ : T_2

n: 1, 2, 3

This block-diagonal matrices will lead to a new set of basis states:

$$\hat{R}_X |\Phi_{i,\Gamma,n}^+(\vec{\delta})\rangle = \sum_{i',\Gamma',n'} |\Phi_{i',\Gamma',n'}^+(\vec{\delta})\rangle [S^{-1} \bar{\Gamma}_{reg}(R_X) S]_{i'\Gamma'n', i\Gamma n}$$

New Method: Basis State (3)

$$\phi_R^+(\vec{x}, \vec{\delta}, t)|\Omega\rangle = |\phi_R^+(\vec{x}, \vec{\delta}, t)\rangle \sim |\phi_R^+(\vec{\delta})\rangle$$

$$\hat{R}_X |\phi_R^+(\vec{\delta})\rangle = |\phi_{R_X R}^+(\vec{\delta})\rangle = \sum_{R'} |\phi_{R'}^+(\vec{\delta})\rangle [\bar{\Gamma}_{reg}(R_X)]_{R'R}$$

$\bar{\Gamma}_{reg}$ is “**regular representation**”.

It can be reduced to several irreducible representations :

$$S^{-1} \bar{\Gamma}_{reg} S = A_1^+ \oplus A_2^+ \oplus 2E^+ \oplus 3T_1^+ \oplus 3T_2^+ \\ \oplus A_1^- \oplus A_2^- \oplus 2E^- \oplus 3T_1^- \oplus 3T_2^-$$

This reduced matrix will lead to new basic states:

$$\hat{R}_X |\Phi_{i,\Gamma,n}^+(\vec{\delta})\rangle = \sum_{i',\Gamma',n'} |\Phi_{i',\Gamma',n'}^+(\vec{\delta})\rangle [S^{-1} \bar{\Gamma}_{reg}(R_X) S]_{i'\Gamma'n', i\Gamma n}$$

$$|\phi_R^+(\vec{\delta})\rangle \xrightarrow{\hspace{15em}} |\Phi_{i,\Gamma,n}^+(\vec{\delta})\rangle$$

$$|\Phi_{i,\Gamma,n}^+(\vec{\delta})\rangle = \sum_R |\phi_R^+(\vec{\delta})\rangle [S]_{R, i\Gamma n}$$

New Method: Basis State (4)

Summary, now we have two sets of basis states, related by the transformation matrix S.

$$|\Phi_{i,\Gamma,n}^+(\vec{\delta})\rangle = \sum_R |\phi_R^+(\vec{\delta})\rangle [S]_{R, i\Gamma n}$$

The representation matrix of these states are satisfied:

$$\hat{R}_X |\phi_R^+(\vec{\delta})\rangle = \sum_{R'} |\phi_{R'}^+(\vec{\delta})\rangle [\bar{\Gamma}_{reg}(R_X)]_{R'R}$$

$$\hat{R}_X |\Phi_{i,\Gamma,n}^+(\vec{\delta})\rangle = \sum_{i',\Gamma',n'} |\Phi_{i',\Gamma',n'}^+(\vec{\delta})\rangle [S^{-1} \bar{\Gamma}_{reg}(R_X) S]_{i'\Gamma'n', i\Gamma n}$$

$$S^{-1} \bar{\Gamma}_{reg} S = A_1^+ \oplus A_2^+ \oplus 2E^+ \oplus 3T_1^+ \oplus 3T_2^+ \\ \oplus A_1^- \oplus A_2^- \oplus 2E^- \oplus 3T_1^- \oplus 3T_2^-$$

We can make matrix S as an unitary matrix, $S^+ = S^{-1}$.

Then the normalization is satisfied:

$$\langle \phi_R^\dagger(\vec{\delta}) | \phi_{R'}^\dagger(\vec{\delta}) \rangle = \delta_{R,R'}$$

$$\langle \Phi_{i,\Gamma,n}^\dagger(\vec{\delta}) | \Phi_{i',\Gamma',n'}^\dagger(\vec{\delta}) \rangle = \delta_{i,i'} \delta_{\Gamma,\Gamma'} \delta_{n,n'}$$

New Method: Correlation Function(1)

The correlation function is:

$$G_{R,R'}(\vec{p} = 0, \vec{y}, \vec{x}, \vec{\delta}, t) = \sum_{\vec{y}-\vec{x} \in \mathbb{Z}^3} e^{\vec{p} \cdot (\vec{y}-\vec{x})} \langle \Omega | \phi_R(\vec{y}, \vec{\delta}, t) \phi_{R'}^\dagger(\vec{x}, \vec{\delta}, 0) | \Omega \rangle$$

$$\sim \sum_{\vec{y}-\vec{x} \in \mathbb{Z}^3} \langle \phi_R^\dagger(\vec{y}, \vec{\delta}, 0) | e^{-\hat{H}t} | \phi_{R'}^\dagger(\vec{x}, \vec{\delta}, 0) \rangle \sim \sum \langle \phi^\dagger(R^{-1}\vec{\delta}) | e^{-\hat{H}t} | \phi^\dagger(R'^{-1}\vec{\delta}) \rangle$$

48×48

10

$$\sum \langle \phi^\dagger(R\vec{\delta}) | e^{-\hat{H}t} | \phi^\dagger(\vec{\delta}) \rangle = \sum \langle \phi^\dagger(R'RR'^{-1}\vec{\delta}) | e^{-\hat{H}t} | \phi^\dagger(\vec{\delta}) \rangle$$

$$= \sum \langle \phi^\dagger(RR'\vec{\delta}) | e^{-\hat{H}t} | \phi^\dagger(R'\vec{\delta}) \rangle = \sum \langle \phi^\dagger(R'R\vec{\delta}) | e^{-\hat{H}t} | \phi^\dagger(R'\vec{\delta}) \rangle$$

