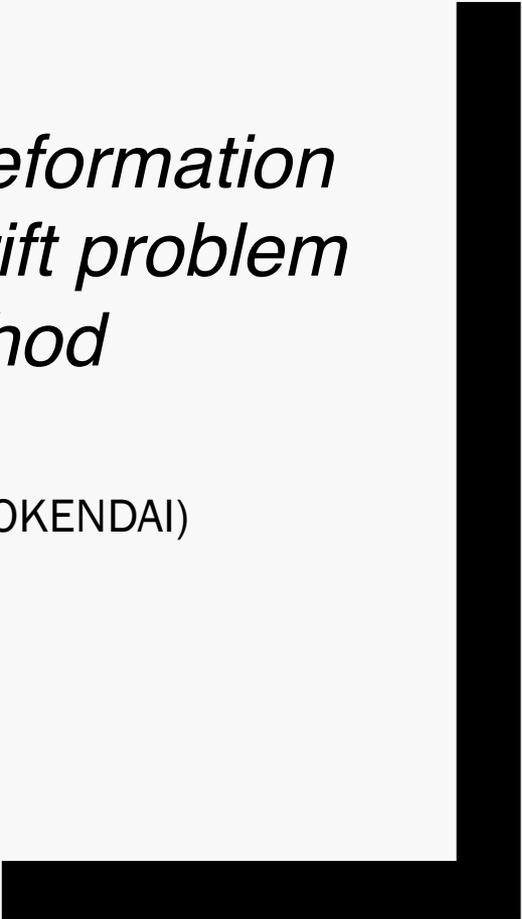


*Comparative studies of the deformation
techniques for the singular-drift problem
in the complex Langevin method*

Yuta Ito (KEK) and Jun Nishimura (KEK,SOKENDAI)



Introduction

The complex Langevin method is a promising approach to the sign problem.

However, in finite density QCD at low temperature and high density, this method does not work due to the **singular-drift problem**.

◆ Singular-drift problem [Nishimura, Shimasaki '15]

- associated with appearance of near-zero eigenvalues of the Dirac operator

➤ We can avoid this problem by **deforming the Dirac operator**. [YI-Nishimura '16]

cf) the application to finite density QCD → Shimasaki's talk

◆ Note, however, that there are many ways to deform the Dirac operator.

It is important to look for a good deformation.

Plan of this talk

- Introduction
- Definition of the toy model
- Deformations of the Dirac operator
- Results
- Summary

Plan of this talk

- Introduction
- **Definition of the toy model**
- Deformations of the Dirac operator
- Results
- Summary

Definition of the toy model

- ◆ the Gaussian matrix model with a fermion determinant [Nishimura '02]

$$Z = \int \prod_{\mu=1}^4 dX_{\mu} \frac{\det D(X)}{\text{complex}} e^{-S_b[X_{\mu}]}$$

$$S_b = \frac{1}{2} N \sum_{\mu=1}^4 \text{tr}(X_{\mu})^2$$

$$D_{i\alpha, j\beta}(X) = \sum_{\mu=1}^4 (\Gamma_{\mu})_{\alpha\beta} (X_{\mu})_{ij}$$

$X_{\mu} : N \times N$ Hermitian matrices

$$\Gamma_{\mu} = \begin{cases} i\sigma_i & \text{for } \mu = 1, 2, 3, \\ \mathbf{1}_2 & \text{for } \mu = 4 \end{cases}$$

- ◆ SO(4) rotational symmetry

→ broken down to SO(2) due to the fermion determinant

(predicted by the Gaussian expansion method)

[Nishimura-Okubo-Sugino '05]

- ◆ To see the SSB, introducing a symmetry breaking term,

$$\frac{N}{2} \text{tr} X_{\mu}^2 \rightarrow \frac{N}{2} (1 + \epsilon_{\mu}) \text{tr} X_{\mu}^2$$

We take the large N limit and then $\epsilon \rightarrow 0$ limit.

Application of the complex Langevin method

- ◆ complex Langevin equation

$$\frac{dX_\mu}{d\tau} = -\frac{dS}{dX_\mu} + \eta_\mu(\tau) \quad \eta_\mu(\tau) : \text{white noise}$$

$$S = \frac{N}{2} (1 + \epsilon_\mu) \text{tr} X_\mu^2 - \ln \det D(X)$$

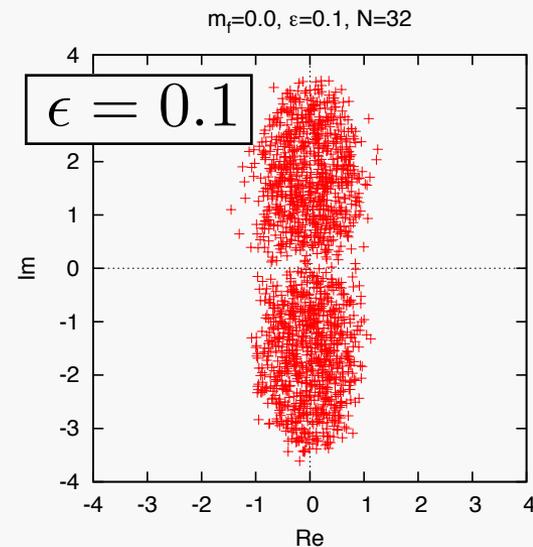
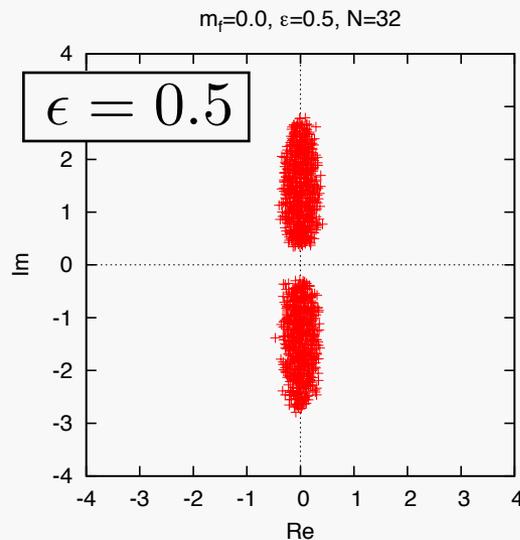
- ◆ drift term

$$\frac{dS}{dX_\mu} = N (1 + \epsilon_\mu) X_\mu - \text{tr}_\alpha (D^{-1} \Gamma_\mu)$$

Appearance of near-zero eigenvalues of the Dirac op.
causes **the singular-drift problem**.

The singular-drift problem

◆ Eigenvalue distribution of the Dirac operator



→ It is difficult to make ϵ_μ sufficiently small.

We consider [the deformation of the Dirac op.](#) to avoid the singular-drift problem and extrapolate the deformation parameter to zero [using only reliable data points.](#)

Plan of this talk

- Introduction
- Definition of the toy model
- Deformations of the Dirac operator
- Results
- Summary

Deformation of the Dirac operator

$$D(X) = \sum_{\mu=1}^4 \Gamma_{\mu} \otimes X_{\mu} \quad \Gamma_{\mu} = \begin{cases} i\sigma_i & \text{for } \mu = 1, 2, 3, \\ \mathbf{1}_2 & \text{for } \mu = 4 \end{cases}$$

To avoid singular-drift problem, we consider **two types of deformation**.

◆ Deformation 1 [YI-Nishimura '16]

$$D(X; m_f) = \sum_{\mu=1}^4 \Gamma_{\mu} \otimes X_{\mu} + \begin{cases} m_f \Gamma_3 \otimes \mathbf{1}_N \\ m_f \Gamma_4 \otimes \mathbf{1}_N \end{cases}$$

: deformation 1A

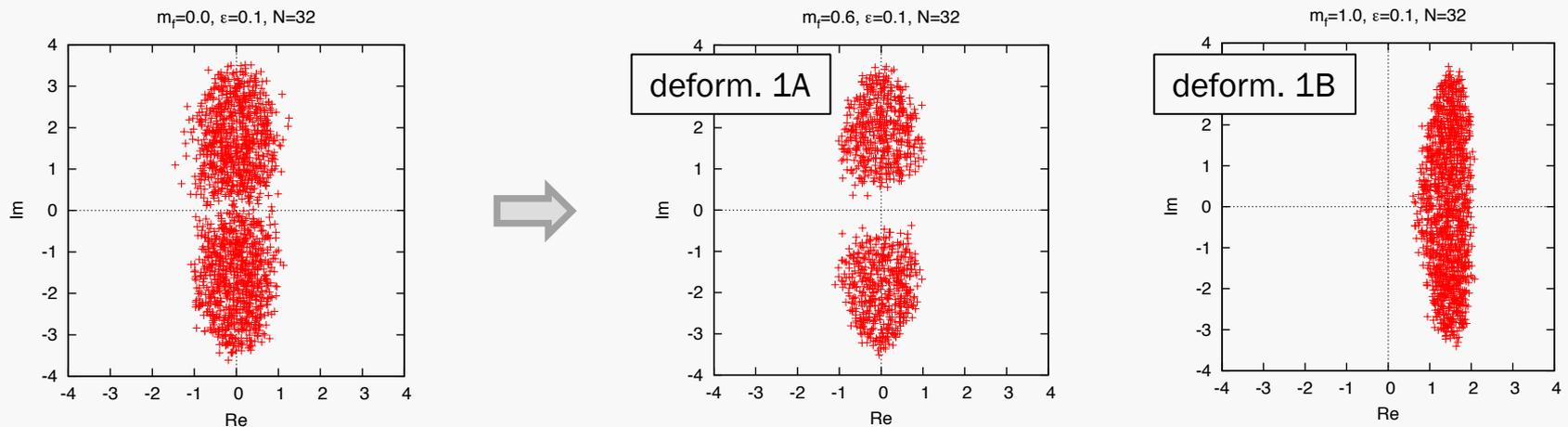
: deformation 1B

$m_f \in \mathbb{R}$: deformation parameter

$m_f \rightarrow 0$

This term **splits or shifts** the eigenvalue distribution.

◆ Eigenvalue distribution



➤ The singularity at the origin is avoided.

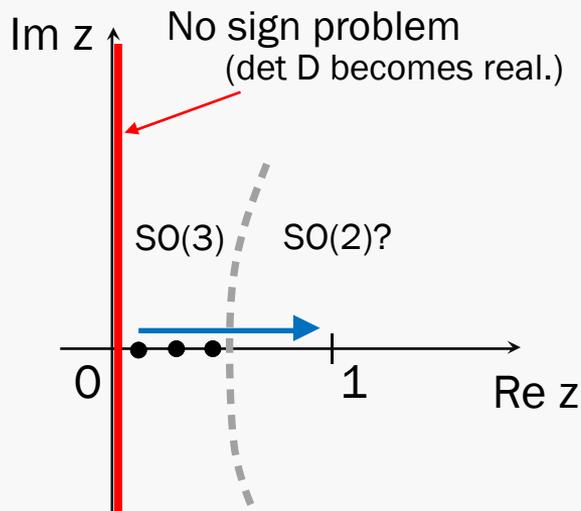
Deformation of the Dirac operator (cont'd)

◆ Deformation 2

$$D(X; z) = \sum_{i=1}^3 \Gamma_i \otimes X_i + z \Gamma_4 \otimes X_4 \quad z \in \mathbb{C}$$

$z=1$: undeformed model

This deformation ($z \neq 1$) breaks $SO(4)$ symmetry to $SO(3)$.



z can be regarded as an analogue of the chemical potential in finite density QCD.

◆ We restrict z to be real and approach $z = 1$.

The phase transition is expected to occur at some z within $0 < z < 1$.

Plan of this talk

- Introduction
- Definition of the toy model
- Deformations of the Dirac operator
- **Results**
- Summary

Observables

- ◆ order parameters for the SSB of SO(4)

$$\rho_{\mu}(\epsilon, m_f) = \lim_{N \rightarrow \infty} \frac{\langle \frac{1}{N} \text{tr} X_{\mu}^2 \rangle_{\epsilon, m_f}}{\sum_{\nu=1}^4 \langle \frac{1}{N} \text{tr} X_{\nu}^2 \rangle_{\epsilon, m_f}}$$

- We take $\epsilon \rightarrow 0$ limit and $m_f \rightarrow 0$ limit.

- ◆ prediction from the Gaussian expansion method

$$\rho_{\mu}(\epsilon = 0, m_f = 0) \simeq \underline{0.35, 0.35}, 0.167, 0.133$$

→ This indicates the SSB from SO(4) to SO(2)

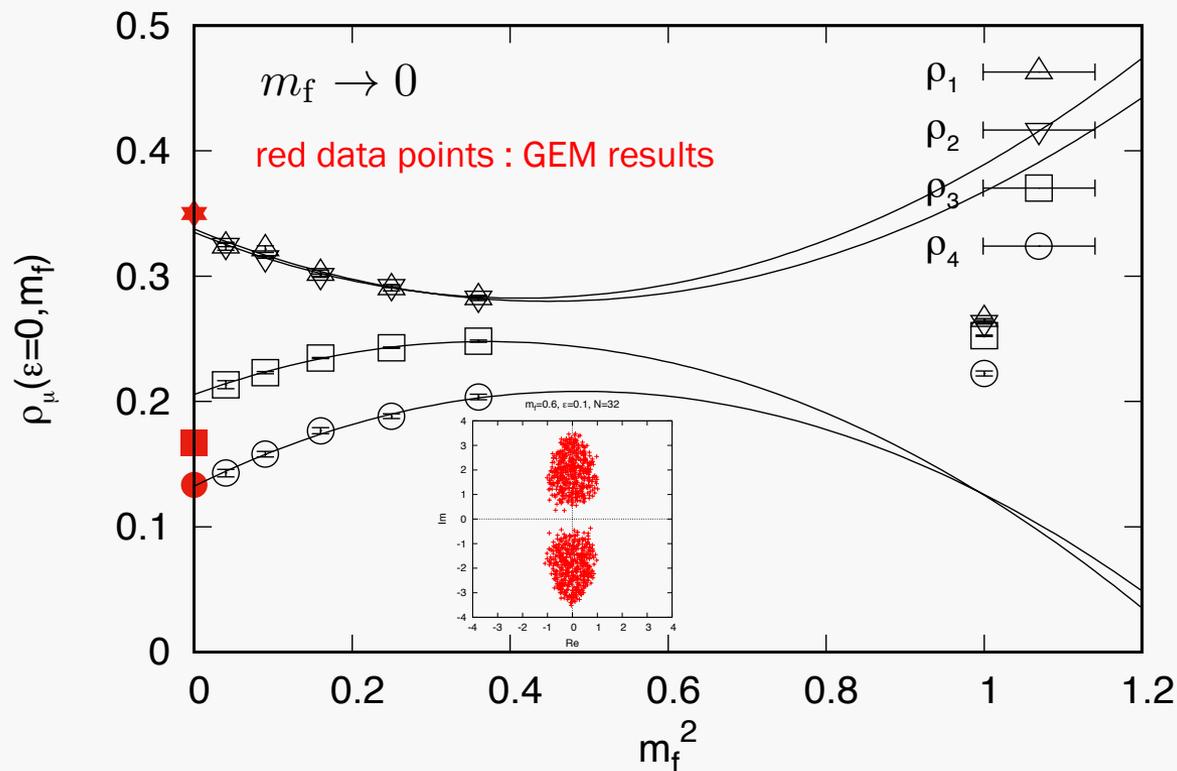
- Note that these results may contain uncontrollable systematic errors.

Results

◆ Deformation 1A

$$D(X; m_f) = \sum_{\mu=1}^4 \Gamma_{\mu} \otimes X_{\mu} + \underline{m_f \Gamma_3 \otimes \mathbf{1}_N} \quad \text{invariant under } m_f \rightarrow -m_f$$

➤ The lines are fits to $f(m_f) = c_1 + c_2 m_f^2 + c_3 m_f^4$

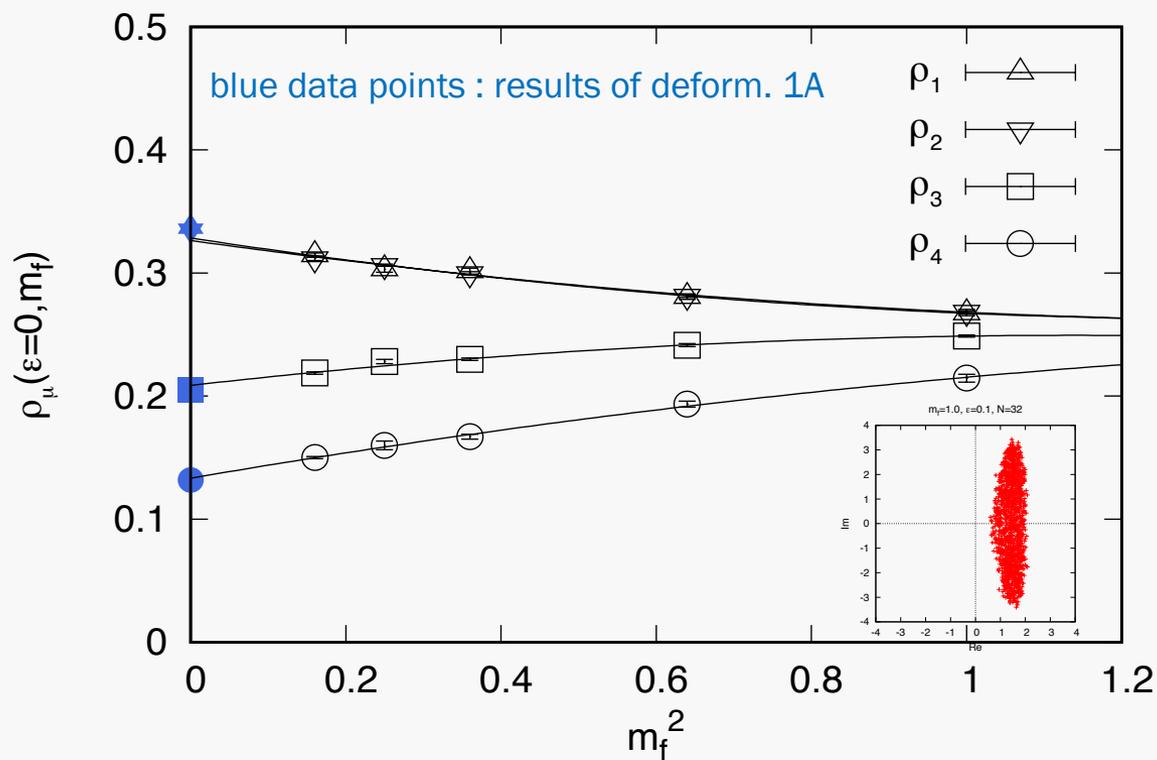


[YI-Nishimura '16]

Results

◆ Deformation 1B

$$D(X; m_f) = \sum_{\mu=1}^4 \Gamma_{\mu} \otimes X_{\mu} + \underline{m_f \Gamma_4 \otimes \mathbf{1}_N} \quad \text{invariant under } m_f \rightarrow -m_f$$



[YI-Nishimura '16]

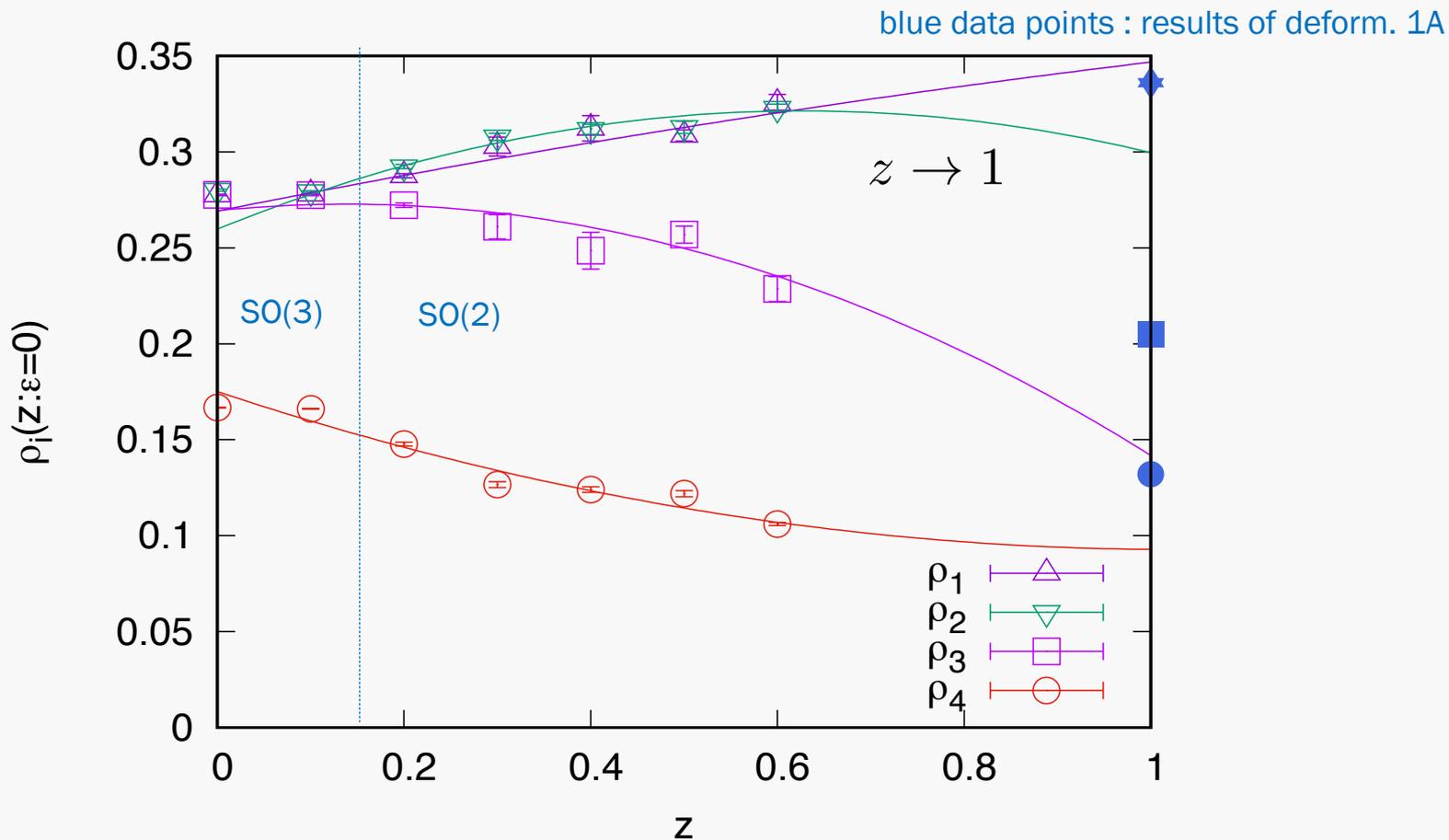
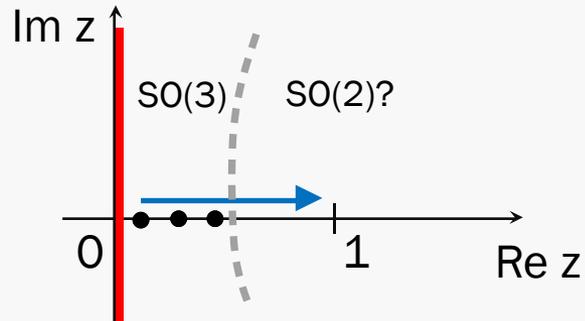
These results are consistent with that of deformation 1A.
This suggests that the GEM results have certain systematic errors.

Results (Preliminary)

◆ Deformation 2

$$D(X; z) = \sum_{i=1}^3 \Gamma_i \otimes X_i + z\Gamma_4 \otimes X_4$$

➤ The lines are fits to $g(z) = c_1 + c_2z + c_3z^2$

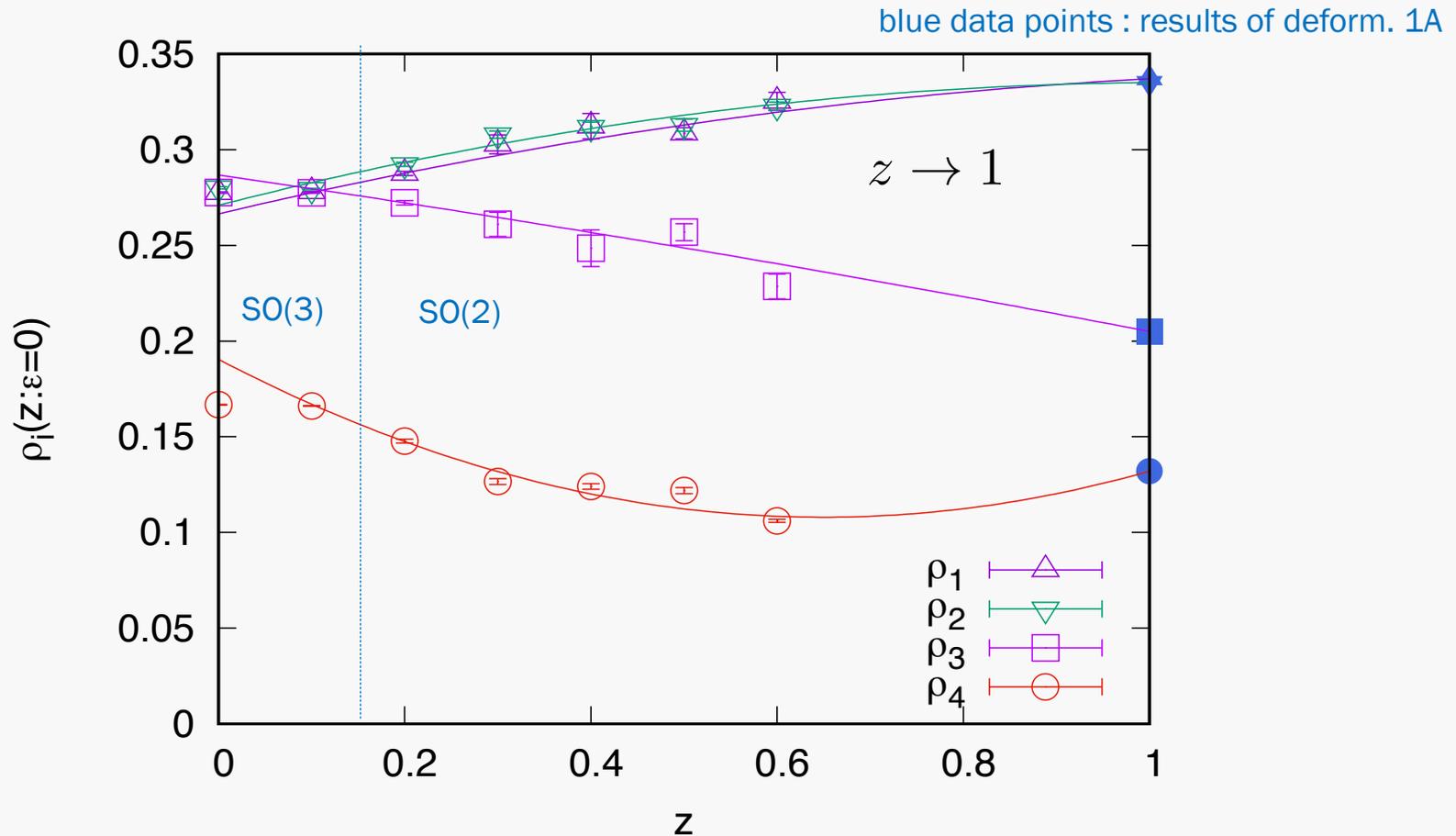


Results (Preliminary)

◆ Deformation 2

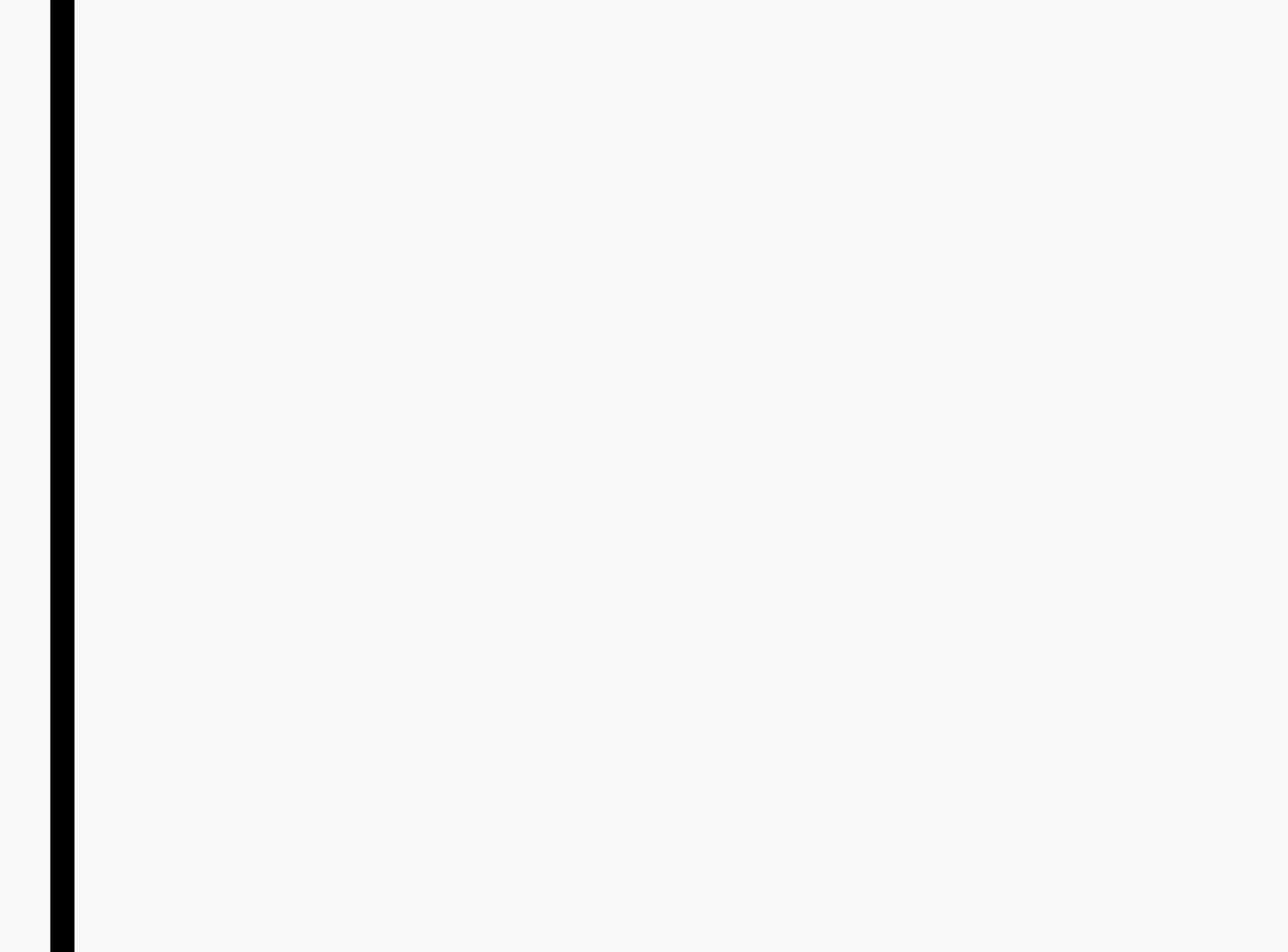
$$D(X; z) = \sum_{i=1}^3 \Gamma_i \otimes X_i + z\Gamma_4 \otimes X_4$$

➤ Fit using the results obtained by the “deformation 1A”.



Summary

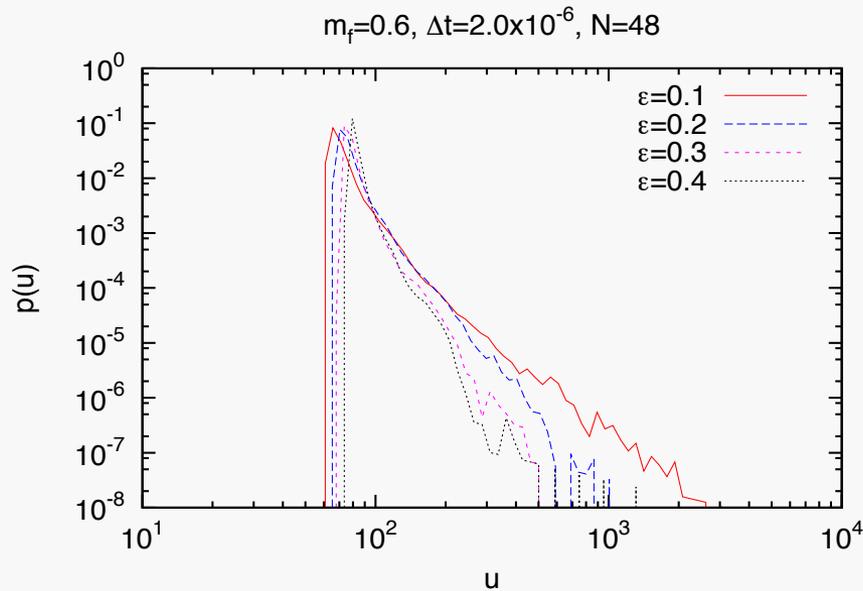
- In order to avoid the singular-drift problem in the CLM, we have deformed the Dirac operator.
- We considered two types of deformation and compared the results.
- After taking $m_f \rightarrow 0$ limit, the results obtained for deformation 1A are consistent with that for deformation 1B, and both the results show the SSB from $SO(4)$ to $SO(2)$.
- However, there is a slight deviation from the prediction by the GEM, which indicates that the result of GEM contains certain systematic errors.
- More calculations are needed for deformation 2.
- Our work implies the importance of trying various deformations and seeing the consistency.



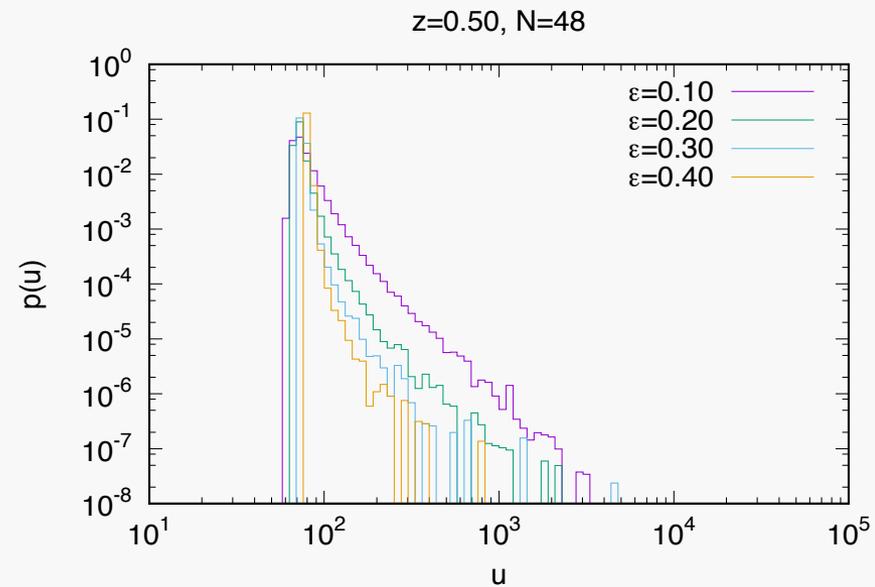
The Validity of the simulations

◆ histogram of the norm of drift

➤ deformation1



➤ deformation2



$$\rho_{\mu}(\epsilon = 0, m_f = 0) \simeq 0.35, 0.35, 0.167, 0.133$$

$$\lim_{m_f \rightarrow 0} \lim_{\epsilon \rightarrow 0} \rho_{\mu}(\epsilon, m_f) = 0.328(4), 0.326(2), 0.208(2), 0.133(2)$$

$$\lim_{m_f \rightarrow 0} \lim_{\epsilon \rightarrow 0} \rho_{\mu}(\epsilon, m_f) = 0.337(6), 0.335(2), 0.205(2), 0.132(4)$$